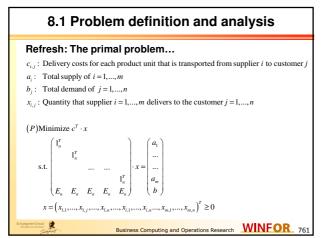
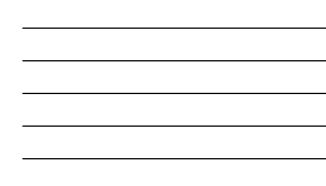
8 Transportation Problem – Alpha-Beta

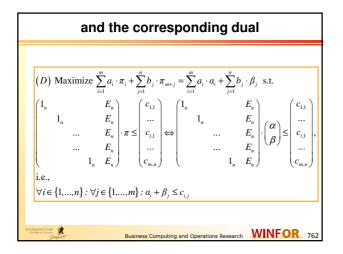
- Now, we introduce an additional algorithm for the Hitchcock Transportation problem, which was already introduced before
- This is the Alpha-Beta Algorithm

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- It completes the list of solution approaches for solving this well-known problem
- The Alpha-Beta Algorithm is a primal-dual solution algorithm
- Owing to the simplicity of the dual problem, this procedure is capable of using significant insights into the problem structure









Direct Observation

- The dual considers a somewhat modified problem
- This may be interpreted as follows

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- There is a third party that offers transportation service between the plants and the consumers
- For this service, both sides have to pay an individual fee. Specifically, the *i*th supplier pays α_i and the *j*th consumer β_j
- Obviously, it is not possible to charge more than c_{i,j} for the respective combination
- Otherwise, since it possesses a more efficient alternative, the company would not make use of this alternative
- Thus, the difference $c_{i,j},\alpha_j,\beta_j$ is denoted as a speculative gain of the considered company
- Consequently, whenever this difference is negative, the primal problem is hold to introduce (i,j) in the basis. Otherwise, we better keep it out.

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The first row of the primal tableau

If we consider the first row of the primal tableau, we directly obtain

$$\overline{c}_{i,j} = c_{i,j} - c_B \cdot A_B^{-1} \cdot A = c_{i,j} - \pi^T \cdot A = c_{i,j} - A^T \cdot \pi$$
$$= c_{i,j} - \alpha_i - \beta_j$$

If we have $\overline{c}_{i,j} < 0$, the dual variables are not feasible and outsourcing is not reasonable.

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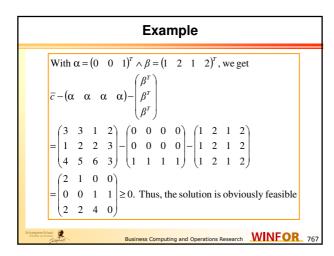
Feasible dual solutions

Obviously, since $c_{i,j} \ge 0$, we have $\pi = 0^{n+m}$ as a trivial initial solution.

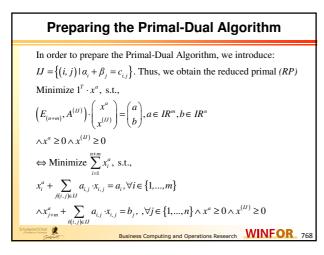
This trivial solution can be directly improved by
$$\begin{split} \beta_{j} &= \min \left\{ c_{i,j} \mid i = 1, ..., m \right\} \\ \wedge \alpha_{i} &= \min \left\{ c_{i,j} - \beta_{j} \mid j = 1, ..., n \right\} \end{split}$$

Consider an example			
$a^{T} = (3 5 6) \land b^{T} = (2 3 6 3) \land c = \begin{pmatrix} 3 & 3 & 1 & 2 \\ 1 & 2 & 2 & 3 \\ 4 & 5 & 6 & 3 \end{pmatrix}$ \Rightarrow			
Generating an initial solution : $\beta = (1 \ 2 \ 1 \ 2)^T \Rightarrow$ $(\min\{2 \ 1 \ 0 \ 2\} \ (0)$			
$\alpha = \begin{pmatrix} \min\{3-1,3-2,1-1,2-2\}\\ \min\{1-1,2-2,2-1,3-2\}\\ \min\{4-1,5-2,6-1,3-2\} \end{pmatrix} = \begin{pmatrix} \min\{2,1,0,0\}\\ \min\{0,0,1,1\}\\ \min\{3,3,5,1\} \end{pmatrix} = \begin{pmatrix} 0\\ 0\\ 1 \end{pmatrix}$			
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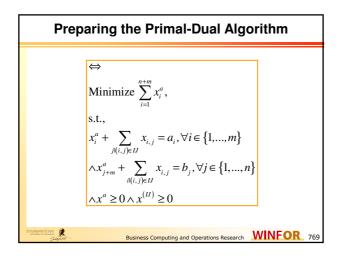




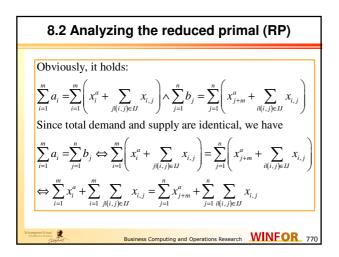




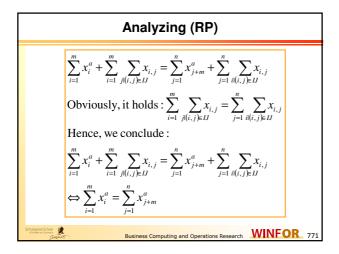




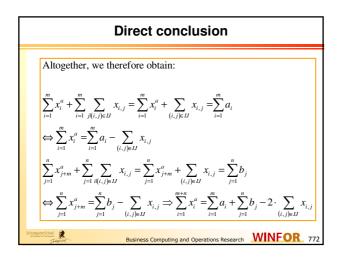




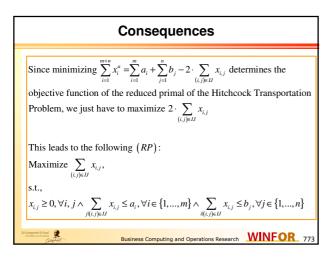




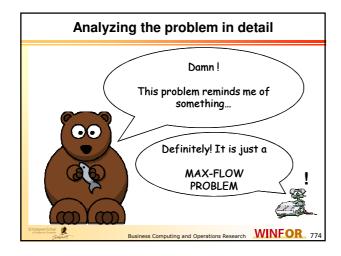


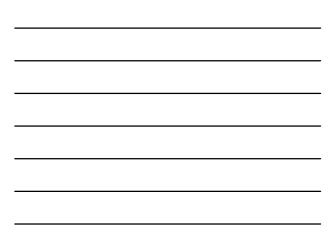






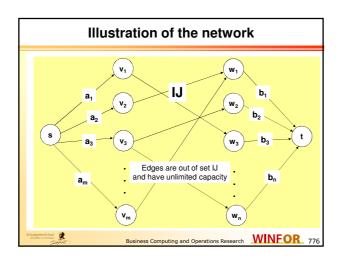




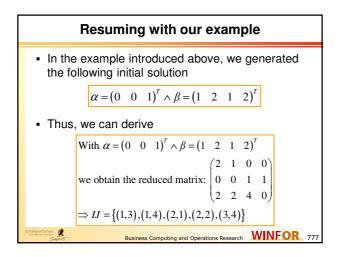


	The RP is a specific Flow Problem			
	Obviously, the problem (RP) can be modeled as			
	a Max-Flow Problem.			
	For this purpose, we define the following network:			
	$V = \{s, v_1,, v_m, w_1,, w_n, t\}$			
	$E = \{(s, v_i) 1 \le i \le m\} \cup \{(v_i, w_j) 1 \le i \le m \land 1 \le j \le n \land (i, j) \in IJ\}$			
	$\cup\{(w_j,t) 1\leq j\leq n\}$			
	$c(s, v_i) = a_i, \forall i \in \{1,, m\} \land c(v_i, w_j) = \infty, \forall (i, j) \in IJ$			
	$\wedge c(w_j, t) = b_j, \forall j \in \{1, \dots, n\}$			
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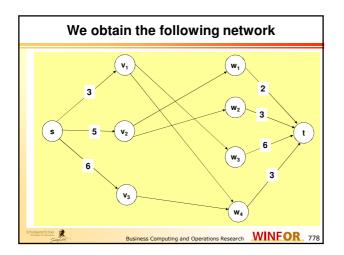




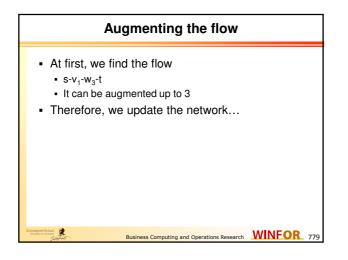


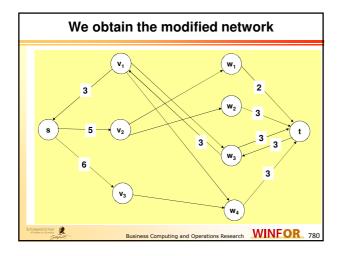




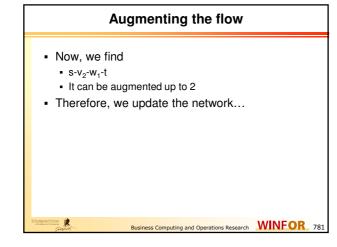


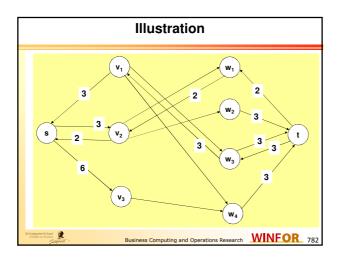


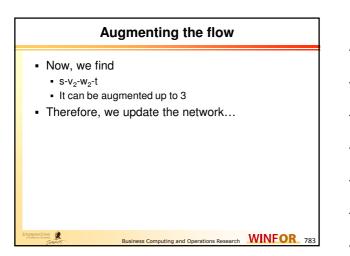


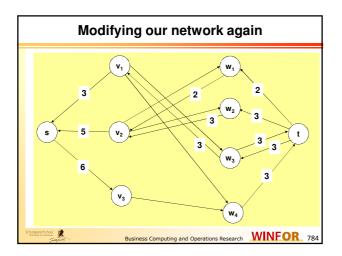




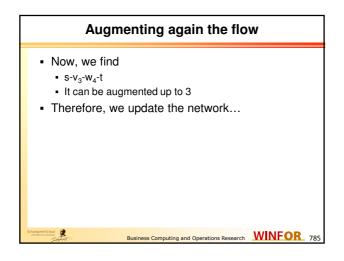


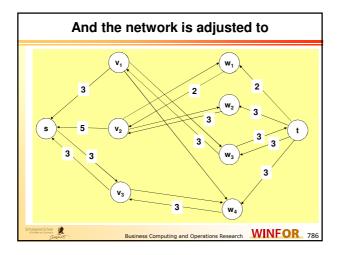


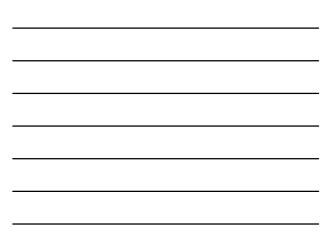






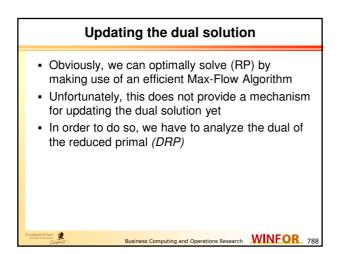


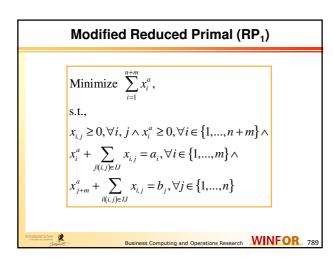




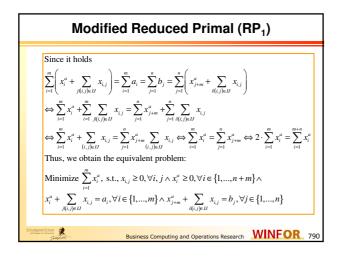
Solution to the reduced primal problem				
Thus, we obtain : $x = \begin{pmatrix} 0 & 0 & 3 & 0 \\ 2 & 3 & 0 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix}$ Obviously <i>x</i> is not feasible for (<i>P</i>) Owing to the vectors $a^{T} = \begin{pmatrix} 3 & 5 & 6 \end{pmatrix} \land$ $b^{T} = \begin{pmatrix} 2 & 3 & 6 & 3 \end{pmatrix}$, we need the vector of slackness variables $x^{a} = \begin{pmatrix} 0 & 0 & 3 & 0 & 0 & 3 & 0 \end{pmatrix}^{T}$				
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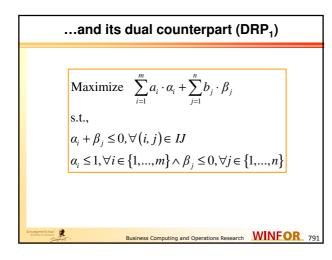


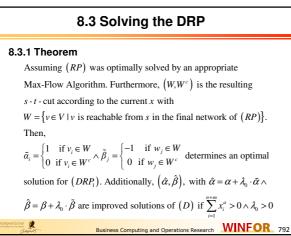










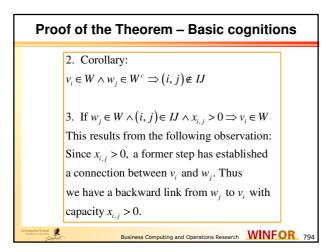


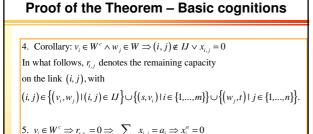
Proof of the Theorem – Basic cognitions

As a preliminary step, we generate some basic attributes

1. If $v_i \in W$, we know that: if additionally $(i, j) \in IJ \Rightarrow w_j \in W$ This results from the following observation: If $v_i \in W \land (i, j) \in IJ$, then we know that there is an edge with unlimited capacity connecting v_i and w_j . Hence, it holds $c_{i,j} > f_{i,j}$ and therefore w_j is reachable from *s* as well.

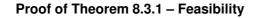
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6.
$$w_j \in W \Rightarrow r_{w_j,t} = 0 \Rightarrow \sum_{a_{i,j} \in E} x_{i,j} = b_j \Rightarrow x_{j+m}^a = 0$$

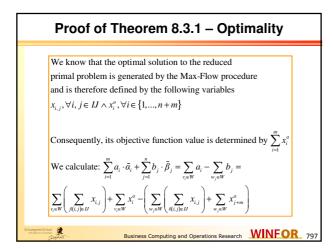
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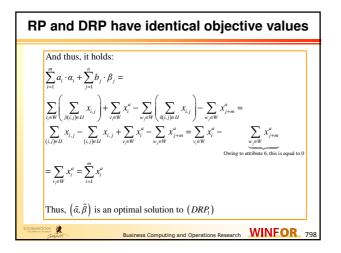
We are now ready to commence the proof. At first, we show the feasibility of the generated solution to (*DRP*). Obviously, it holds:

1. $\tilde{\alpha}_i \leq 1, \forall i \in \{1, ..., m\} \land \tilde{\beta}_j \leq 0, \forall j \in \{1, ..., n\}$ Additionally, we have to show 2. $\tilde{\alpha}_i + \tilde{\beta}_j \leq 0, \forall (i, j) \in IJ$. 2.1 $v_i \in W \Rightarrow w_j \in W \Rightarrow \tilde{\alpha}_i = 1 \land \tilde{\beta}_j = -1 \Rightarrow \tilde{\alpha}_i + \tilde{\beta}_j = 0$ 2.2 $v_i \in W^c \Rightarrow \tilde{\alpha}_i = 0 \Rightarrow \tilde{\alpha}_i + \tilde{\beta}_j \leq 0$ Thus, $(\tilde{\alpha}_i, \tilde{\beta}_j)$ is a feasible solution to (DRP).

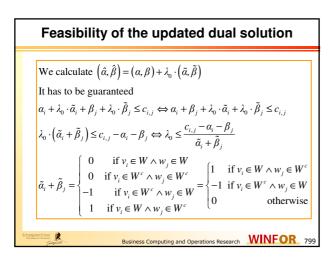
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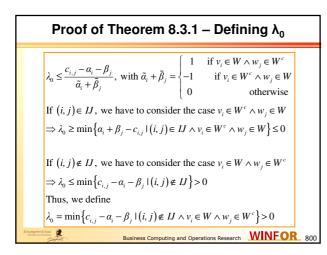


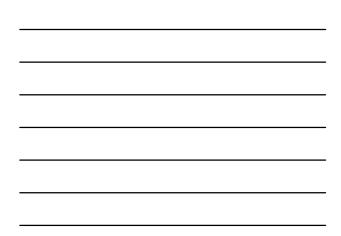


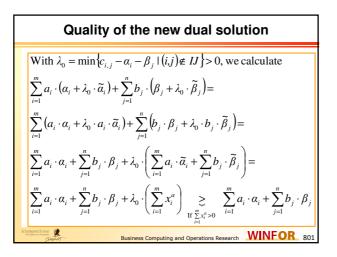




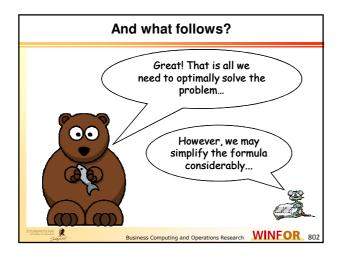








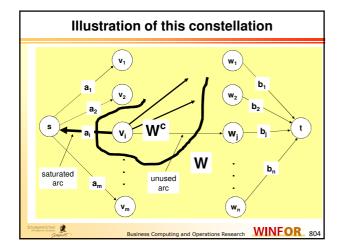






Important observation – Part 1

We consider the resulting constellation after applying the Max-Flow procedure. Addionally, we analyze the generated flow $x_{i,j}$. First of all, we consider arcs that vanish in the next iteration. This may happen only if $(i, j) \in IJ$ in the current iteration, but in the next one it holds $(i, j) \notin IJ$. This case is characterized that originally $\alpha_i + \beta_j = c_{i,j}$ applies, but subsequently $\hat{\alpha}_i + \hat{\beta}_j < c_{i,j}$ holds. Note that this is only possible if $\tilde{\alpha}_i + \tilde{\beta}_j < 0 \Rightarrow \tilde{\alpha}_i + \tilde{\beta}_j = -1$. This is the constellation $v_i \in W^c \land w_j \in W$. It is illustrated on the next slide. Here, we directly conclude that the arc $(i, j) \in IJ$ was not used by the generated flow at all. Hence, we obtain $x_{i,j} = 0$.





Consequence

- If we erase the edge (i,j) in the subsequent iteration, i.e., the solving of the modified (RP), this has no impact on the current flow x_{i,j}
- Note that the current flow does not make use of this arc
- Consequently, this arc is dispensable

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Observations II

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Now we consider arcs $(i, j) \in IJ$ with $x_{i,j} > 0$. We know that it holds $\hat{a}_i + \hat{\beta}_j = c_{i,j} \implies \tilde{a}_i + \tilde{\beta}_j = 0$. Therefore, the flow $x_{i,j} > 0$ can be kept on these arcs.

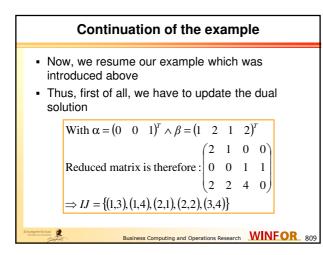
Anyhow, the resulting flow $x_{i,j}$ can be kept for the next iteration of solving (*RP*) that arises after updating α and β . Note that this update may cause additional arcs between the v_i – and w_j – nodes.

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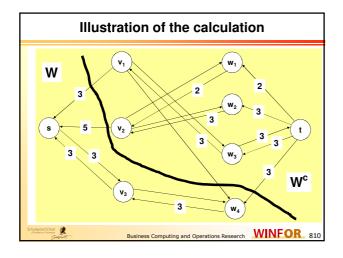
 $\begin{aligned} & \lambda_{0} = \min \left\{ c_{i,j} - \alpha_{i} - \beta_{j} \mid (i,j) \notin IJ \land v_{i} \in W \land w_{j} \in W^{c} \right\} \\ & \text{Thus, we can label all rows } i \text{ in the reduced matrix} \\ & \left(c_{i,j} - \alpha_{i} - \beta_{j} \right) \text{ with } v_{i} \in W^{c}. \text{ Additionally, we label all columns } j \text{ with } w_{j} \in W. \\ & \text{Then } \lambda_{0} \text{ is determined by the minimum unlabeled value.} \\ & \text{We update } \left(c_{i,j} - \hat{\alpha}_{i} - \hat{\beta}_{j} \right) \text{ by applying the following rules:} \end{aligned}$

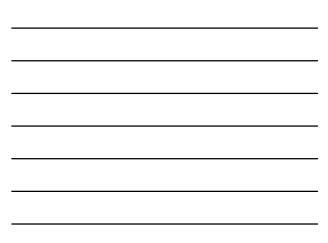
Updating rules				
We distinguish:				
1. If (i, j) is unlabeled $\Rightarrow v_i \in W \land w_j \in W^c$				
\Rightarrow We subtract λ_0 from $c_{i,j} - \alpha_i - \beta_j$				
2. If (i, j) is labeled twice $\Rightarrow v_i \in W^c \land w_j \in W$				
$\Rightarrow \alpha_i + \beta_j = -1$. We add λ_0 to $c_{i,j} - \alpha_i - \beta_j$				
3. If (i, j) is labeled only by the <i>i</i> th row or the <i>j</i> th column				
$\Rightarrow (v_i \in W \land w_i \in W) \lor (v_i \in W^c \land w_i \in W^c) \Rightarrow \alpha_i + \beta_i = 0$				
$c_{i,j} - a_i - \beta_j$ is kept unchanged				
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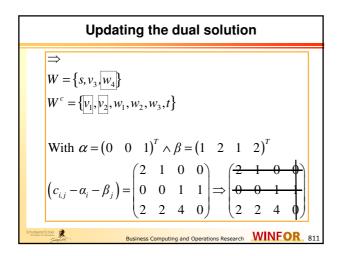




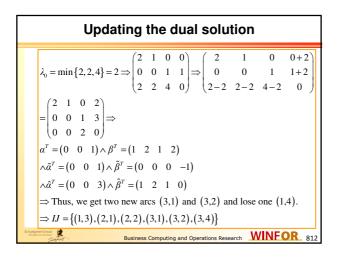




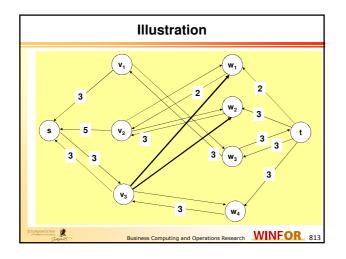




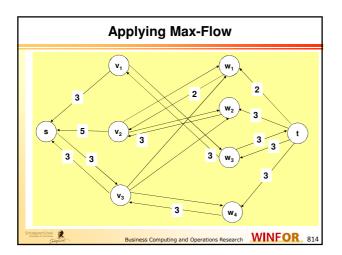




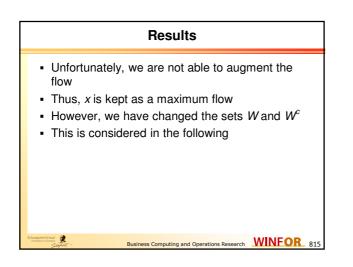


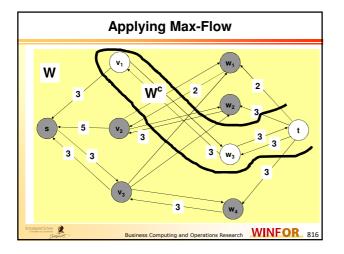




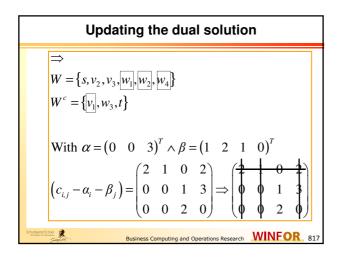








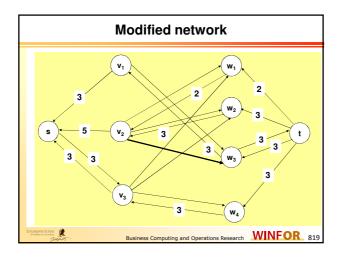




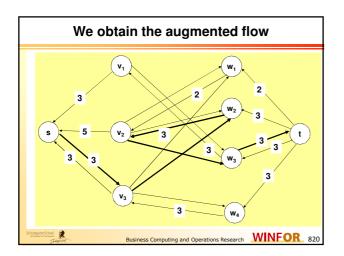


Updating the dual solution				
$\lambda_{0} = \min\{2,1\} = 1 \Rightarrow \begin{pmatrix} 2 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 2 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 3 & 2 & 0 & 3 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 1 & 0 \end{pmatrix}$ $\alpha^{T} = \begin{pmatrix} 0 & 0 & 3 \end{pmatrix} \land \beta^{T} = \begin{pmatrix} 1 & 2 & 1 & 0 \end{pmatrix}$ $\land \tilde{\alpha}^{T} = \begin{pmatrix} 0 & 1 & 1 \end{pmatrix} \land \tilde{\beta}^{T} = \begin{pmatrix} -1 & -1 & 0 & -1 \end{pmatrix}$ $\Rightarrow \tilde{\alpha}^{T} = \begin{pmatrix} 0 & 1 & 4 \end{pmatrix} \land \tilde{\beta}^{T} = \begin{pmatrix} 0 & 1 & 1 & -1 \end{pmatrix}$ $\Rightarrow \text{Thus, we get a new arcs (2,3).}$ $\Rightarrow IJ = \{(1,3), (2,1), (2,2), (2,3)(3,1), (3,2), (3,4)\}$				
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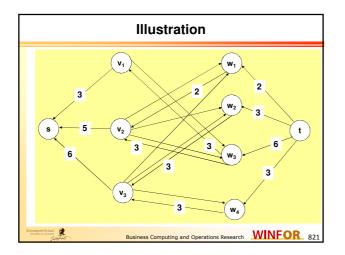




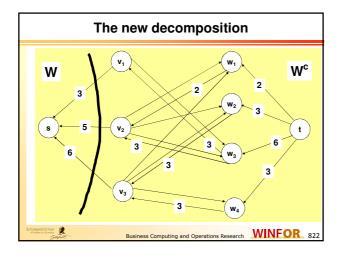


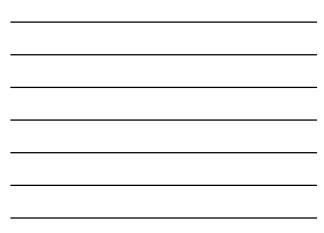










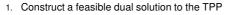


The modified primal solution			
$\Rightarrow W = \{s,\} \land W^c = \{v_1, v_2, v_3, w_1, w_2, w_3, w_4, t\}$ With $\alpha = (0 \ 1 \ 4)^T \land \beta = (0 \ 1 \ 1 \ -1)^T$ $x = \begin{pmatrix} 0 & 0 & 3 & 0 \\ 2 & 0 & 3 & 0 \\ 0 & 3 & 0 & 3 \end{pmatrix}$ $\Rightarrow \text{ Is feasible for } a^T = (3 \ 5 \ 6) \land b^T = (2 \ 3 \ 6 \ 3)$			
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Proof of optimality		
$\Rightarrow W = \{s,\}$	$\wedge W^{c} = \{v_{1}, v_{2}, v_{3}, w_{1}, w_{2}, w_{3}, w_{4}, t\}$	
$\Rightarrow x_i^a = 0, \forall$	$\forall i \in \{1, \dots, m+n\}$ and it holds:	
	$+1 \cdot 2 + 3 \cdot 2 + 5 \cdot 3 + 3 \cdot 3 = 35$	
	$\beta = 3 \cdot 0 + 5 \cdot 1 + 6 \cdot 4 + 2 \cdot 0 + 3 \cdot 1 + 6 \cdot 1 - 3 \cdot 1$ 6 + 6 - 3 = 38 - 3 = 35	
= 3 + 24 + 5	1+0-3=38-3=35	
$\Rightarrow x \text{ and } (a)$	(α, β) are optimal solutions!	
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Alpha-Beta-Algorithm



- Set $\beta_j = \min\{c_{ij} \mid i = 1, ..., m\}$ and $\alpha_i = \min\{c_{ij} \beta_j \mid j = 1, ..., n\}$
- Calculate the matrix with the reduced costs $\overline{c}_{ij} = c_{ij} \alpha_i \beta_j$
- 2. Prepare the network for the Max-Flow-Calculation

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- Nodes: $s, v_1, ..., v_m, w_1, ..., w_n, t$ Arcs: $(s, v_1), ..., (s, v_n)$ with capacity $\frac{a_1, ..., a_m}{b_1, ..., b_n}$ 3. Furthermore: If and only if $\overline{c_{ij}} = 0$, the arc (v_i, w_j) exists with infinite capacity
- 4. Calculate the Maximum s-t-Flow in the network. Let *w* be the set of nodes reachable from node s in the corresponding s-t-Cut
- 5. While $W \neq \{s\}$, conduct the following steps (see next slide):

Alpha-Beta-Algorithm (Dual Solution Update)

- If $v_i \in W \Rightarrow \tilde{\alpha}_i = 1; v_i \in W^c \Rightarrow$, label the *i*-th row in the reduced cost matrix.
- If $w_i \in W \Rightarrow \tilde{\beta}_i = -1 \Rightarrow$, label the *j*-th column in the reduced . cost matrix.
- All other variables of the DRP-solution $\tilde{\alpha}, \tilde{\beta}$ are set to 0.
- Set $\lambda_{\rm p}$ to the minimum value of the unlabeled entries in the reduced cost matrix.
- Subtract $\lambda_{\!\scriptscriptstyle 0}$ from every unlabeled entry and add it to every . entry labeled twice in the reduced cost matrix.
- Set $\beta = \beta + \lambda_0 \tilde{\beta} \wedge \alpha = \alpha + \lambda_0 \tilde{\alpha}$.
- Update the network as indicated by the new reduced cost . matrix.
- Try to augment the current flow and update the set W. . 2
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