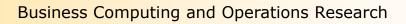
5 The Primal-Dual Simplex Algorithm

- Again, we consider the primal program given as a minimization problem defined in standard form
- This algorithm is based on the cognition that both optimal solutions, i.e., the primal and the dual one, are strongly interdependent
- Specifically, the approach commences the searching process with a feasible dual solution and simultaneously observes the complementary slackness between the solution value of the dual and a primal solution
- If this slackness becomes zero, the optimality of the generated solutions is proven and the calculation process is terminated

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Invariants of the Primal Simplex

While conducting the Primal Simplex, the following attributes are always fulfilled for a minimization problem:

(P) Minimize $c^T \cdot x$, s.t. $A \cdot x = b \land x \ge 0$

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1.
$$c^T \cdot x^0 = c_B^T \cdot x_B^0 + c_N^T \cdot x_N^0 = c_B^T \cdot A_B^{-1} \cdot b = \pi^T \cdot b = b^T \cdot \pi$$

2. $\overline{c}^T \cdot x^0 = \overline{c}_B^T \cdot x_B^0 + \overline{c}_N^T \cdot x_N^0 = 0 \cdot x_B^0 + \overline{c}_N^T \cdot 0 = 0$,
with $\overline{c}^T = c^T - c_B^T \cdot A_B^{-1} \cdot A$

Thus, if $\overline{c}^T \ge 0 \Rightarrow c_B^T \cdot A_B^{-1} \cdot A = \pi^T \cdot A \le c^T \Rightarrow \pi$ is feasible for (D) Maximize $b^T \cdot \pi$, s.t. $A^T \cdot \pi \le c \wedge \pi$ free



Consequences

- The Primal Simplex works on a feasible primal solution that is iteratively improved by basis changes
- This is done by the consideration of a corresponding dual solution that has an identical objective function value
- As long as this dual solution is infeasible, the corresponding entries are inserted in the primal solution in order to fulfill them exactly in the dual program (→Elimination of the corresponding slackness)
- If the dual solution becomes feasible as well the optimality of both solutions (the primal and the dual solution) is proven





The Primal-Dual Simplex

- As mentioned above, we assume that the primal program is given as a minimization problem in standard form
- In what follows, we introduce a new algorithm that commences the searching process with a feasible dual solution
- This solution is analyzed according to a specific relationship to the primal problem in order to generate a corresponding primal solution that allows to prove optimality
- Specifically, we formulate a reduced problem that either generates an optimal primal solution or, if this is not possible, allows a correction of the dual one
- Obviously, this process is executed until the first case applies





Observation

5.1 Theorem of Complementary Slackness Assuming there is a Linear Program in standard form and x and π are feasible solutions to (P) and (D), respectively.

Then, it holds:

x and
$$\pi$$
 are optimal $\Leftrightarrow (c^T - \pi^T \cdot A) \cdot x = 0$





Proof of Theorem 5.1

- Fortunately, this proof is quite easy to conduct
- Based on the facts we already know about tuples of optimal primal and dual solutions, we derive

Specifically, it holds:

$$(c^T - \pi^T \cdot A) \cdot x = 0 \Leftrightarrow c^T \cdot x - \pi^T \cdot A \cdot x = 0$$

Since *x* is feasible for (*P*)
 $\Leftrightarrow c^T \cdot x - \pi^T \cdot b = 0 \Leftrightarrow c^T \cdot x = \pi^T \cdot b$
 $\Leftrightarrow x$ and π are optimal solutions





Direct consequence of Theorem 5.1

5.2 Observation

Assuming x and π are feasible solutions to (P) and (D), respectively.

Additionally, assume that it holds: $(c^T - \pi^T \cdot A) \cdot x = 0.$

Thus, *x* and π are optimal solutions to (*P*) and (*D*), respectively and it holds: $c^T - \pi^T \cdot A \ge 0 \land x \ge 0$

Hence, we can conclude

$$\left(c_{j} - \pi^{T} \cdot a^{j}\right) \cdot x_{j} = 0, \forall j \in \{1, ..., n\}$$
$$\Leftrightarrow x_{j} = 0 \lor \pi^{T} \cdot a^{j} = c_{j}, \forall j \in \{1, ..., n\}$$



A simple example

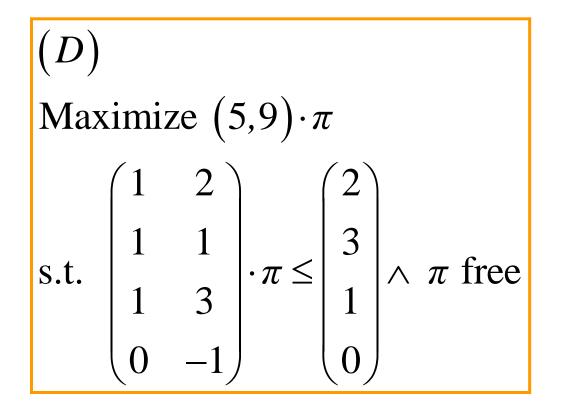
Consider the following Linear Program

(P)Minimize $(2,3,1,0) \cdot x$ s.t. $\begin{pmatrix} 1 & 1 & 1 & 0 \\ 2 & 1 & 3 & -1 \end{pmatrix} \cdot x = \begin{pmatrix} 5 \\ 9 \end{pmatrix} \land x \ge 0$





Example – Thus, we get the following (D)







Example – How to generate π ?

Obviously,
$$x = \begin{pmatrix} 0 \\ 0 \\ 5 \\ 6 \end{pmatrix}$$
 is a feasible solution to (P) .
Thus, we have $x_1 = x_2 = 0 \land x_3, x_4 \neq 0$. Consequently, we need a π with the following attributes
1. $\forall i \in \{3,4\} : \pi^T \cdot a^i = c_i \Leftrightarrow \pi^T \cdot \begin{pmatrix} 1 & 0 \\ 3 & -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
2. π is feasible for (D)





Example – How to generate π ?

Obviously,
$$\pi = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 fulfills both restrictions and, therefore,
we have shown that
 $x = \begin{pmatrix} 0 \\ 0 \\ 5 \\ 6 \end{pmatrix}$ and $\pi = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ are optimal solutions to (P) and (D) ,
respectively.



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A feasible solution to (D)

- For what follows, we need at first a feasible solution to the dual problem. Fortunately, this is quite simple to provide.
- If *c* is positive, we just make use of $\pi=0$.
- Otherwise, we apply the following simple procedure that is depicted next.





Generating a feasible dual solution

- In order to generate a feasible dual solution to cases where c≥0 does not apply, we provide the following simple construction procedure
 - 1. We introduce a n + 1th variable x_{n+1} as well as a m + 1th equality in (*P*)

$$x_1 + x_2 + \dots + x_n + x_{n+1} = \sum_{i=1}^{n+1} x_i = b_{m+1}$$
, with b_{m+1} as a huge

number.

Since we add $c_{n+1} = 0$, we know that this restriction has no impact on the optimal solutions.





Generating a feasible dual solution

2. Consider now the dual program.
Maximize
$$b^T \cdot \pi + b_{m+1} \cdot \pi_{m+1}$$

 $A^T \cdot \pi + (\pi_{m+1} \dots \pi_{m+1})^T \leq c \wedge \pi_{m+1} \leq 0$, i.e.,
 $\forall j : \pi^T \cdot a^j + \pi_{m+1} \leq c_j$
3. We generate $\pi^{ini} = (\pi_1^{ini}, \dots, \pi_{m+1}^{ini})^T$ as follows:
 $\pi_1^{ini} = \pi_2^{ini} = \dots = \pi_m^{ini} = 0 \wedge \pi_{m+1} = \min \{c_j \mid c_j < 0\} < 0$
Thus, since $j \in \{1, \dots, n\}$ exists with $c_j < 0$,
 π^{ini} is feasible for (D) .

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The set J

Assume π to be a feasible solution to the dual program of a Linear Program in standard form. An index $j \in \{1,...,n\}$ is denoted as feasible if and only if it holds: $\pi^T \cdot a^j = c_j$.

We introduce J as the set of feasible indices, i.e., $J = \left\{ j \mid j \in \{1, ..., n\} \land \pi^T \cdot a^j = c_j \right\}.$





Reduced primal problem (RP)

We assume
$$J = \{j_1, ..., j_k\}, k \ge 0$$
 and define
 $A_J = (a^{j_1}, ..., a^{j_k})$ and $x^T = (x^a, x^J)$,
with $x^a = (x_1^a, ..., x_m^a)$ as slack variables.
Then (RP) is defined as follows:
Minimize $\xi_0 = 1^T \cdot x^a$, s.t. $(E_m, A_J) \cdot \begin{pmatrix} x^a \\ x^J \end{pmatrix} = b$, with $\begin{pmatrix} x^a \\ x^J \end{pmatrix} \ge$
is denoted as the reduced primal problem.





Observations

- (RP) is solvable. Specifically, we can use $x^T = (b, 0)$
- Since this trivial solution has the objective function value 1^T.b and this objective function is lower bounded by 0, (RP) is bounded
- Thus, (RP) has always a well-defined optimal solution
- Obviously, this optimal solution comprises two parts
 - First, there are the slackness variables. If these are zero, the objective function value is zero as well. Then, the primal solution is optimal to (P)
 - Secondly, there are the original variables that correspond to the set J. Since the corresponding dual values are equal to the c-vector, only these variables may become unequal to zero





Main conclusion

5.3 Theorem

(RP) always has an optimal solution. If $1^T \cdot x^a = \xi_0 = 0$, $\begin{pmatrix} 0 \\ x^J \end{pmatrix}$ is an optimal solution to (P).

Otherwise, if $\xi_0 > 0$, then the optimal solution to the dual of (*RP*) always generates an improved solution to (*D*).





At first, we assume $\xi_0 = 0$. Thus, we know that $x^a = 0$. Consequently, it holds: $A^{J} \cdot x^{J} = b$. Thus, we consider $\hat{x} = \begin{pmatrix} 0 \\ x^J \end{pmatrix} \ge 0 \Longrightarrow A \cdot \hat{x} = b \wedge \left(c^T - \pi^T \cdot A\right) \cdot x$ $= (c^{T} - \pi^{T} \cdot A)_{I} \cdot x_{J} + (c^{T} - \pi^{T} \cdot A)_{I^{c}} \cdot x_{J^{c}} = 0 \cdot x_{J} + (c^{T} - \pi^{T} \cdot A)_{I^{c}} \cdot 0 = 0$ Hence, x and π are optimal solutions to the Linear Programs (P) and (D), respectively.





Now, we consider the case $\xi_0 > 0$. Thus, we know that $x^a \neq 0$. Consequently, it holds: $A^J \cdot x^J \neq b$.

Let us now consider the dual of (RP), denoted as (DRP)(RP)

Minimize
$$1^T \cdot x^a$$
, s.t. $\left(E_m, A^J\right) \cdot \begin{pmatrix} x^a \\ x^J \end{pmatrix} = b, x^T = \left(x^a, x^J\right) \ge 0$

Thus, we obtain (DRP) as follows

Maximize
$$b^T \cdot \pi$$
, s.t. $\begin{pmatrix} E_m \\ (A^J)^T \end{pmatrix} \cdot \pi \leq \begin{pmatrix} 1^m \\ 0^{|J|} \end{pmatrix}$, π free





Assuming $\tilde{\pi}$ is an optimal solution to (DRP). Then, we conclude $b^T \cdot \tilde{\pi} = \xi_0 > 0$. Furthermore, let $\pi' = \pi + \lambda \cdot \tilde{\pi}$. We compute $b^T \cdot \pi' = b^T \cdot (\pi + \lambda \cdot \tilde{\pi}) = b^T \cdot \pi + b^T \cdot \lambda \cdot \tilde{\pi} = b^T \cdot \pi + \lambda \cdot b^T \cdot \tilde{\pi} = b^T \cdot \pi + \lambda \cdot \xi_0 > b^T \cdot \pi$.

Consequently, if π' is feasible for (D), π' outperforms π . Hence, we now have to determine suitable values for λ resulting in feasible values for π' .





Note that it holds: π' feasible for (D) $\Leftrightarrow \forall j : c_j - \pi'^T \cdot a^j \ge 0$ $\Leftrightarrow \forall j : c_j - (\pi + \lambda \cdot \tilde{\pi})^T \cdot a^j \ge 0$ $\Leftrightarrow \forall j : c_j - \pi^T \cdot a^j - \lambda \cdot \tilde{\pi}^T \cdot a^j \ge 0$ $\Leftrightarrow \forall j : c_j - \pi^T \cdot a^j \ge \lambda \cdot \tilde{\pi}^T \cdot a^j$





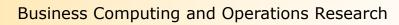
$$\begin{aligned} \forall j : c_j - \pi^T \cdot a^j &\geq \lambda \cdot \tilde{\pi}^T \cdot a^j \\ \text{Since } \pi \text{ is feasible for } (D), \text{ we know that } c_j - \pi^T \cdot a^j &\geq 0. \\ \text{Let us now consider the corresponding final tableau of } (RP) \\ \Rightarrow \\ \frac{0}{b} \begin{vmatrix} 1^T & 0^T & 0^T \\ E_m & A^J & A^{J^c} \end{vmatrix} \Rightarrow \frac{-\xi_0}{-\xi_0} \begin{vmatrix} 1^T - \tilde{\pi}^T & 0^T - \tilde{\pi}^T \cdot A^J & 0^T - \tilde{\pi}^T \cdot A^{J^c} \\ \dots & \dots & \dots & \dots \\ &\Rightarrow 0^T - \tilde{\pi}^T \cdot A^J &\geq 0 \Leftrightarrow \tilde{\pi}^T \cdot A^J &\leq 0 \Rightarrow \forall j \in J : \tilde{\pi}^T \cdot a^j \leq 0 \\ \text{Hence, if } j \in J \land \lambda > 0, \text{ the feasibility restriction is always fulfilled.} \end{aligned}$$

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Summary – The algorithm

- 1. We commence the searching process with a feasible solution π to the dual program (D).
- 2. Then, we generate the reduced Linear Program $(RP(\pi))$ and solve it optimally. Thus, we distinguish altogether three cases:

1.
$$\xi_0 = 0$$

 \Rightarrow The tableau provides an optimal solution to (P) .





Summary – The algorithm

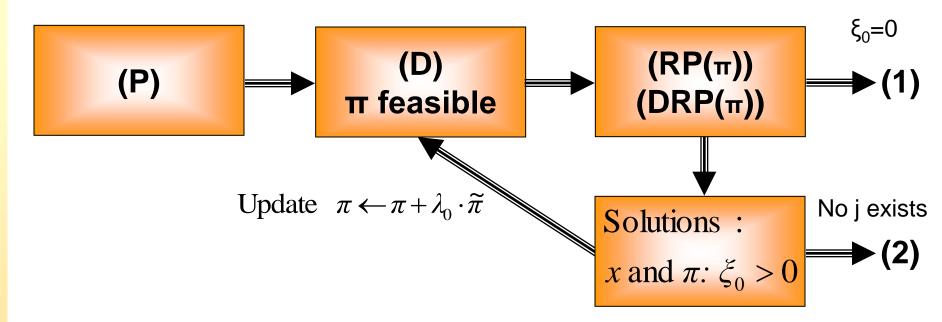
Further cases (Continuation of step 2)

2. $\xi_0 > 0 \land \forall j : \tilde{\pi}^T \cdot a^j \leq 0 \Rightarrow$ The primal problem (P) is not solvable. 3. $\xi_0 > 0 \land \exists j : \tilde{\pi}^T \cdot a^j > 0$ \Rightarrow Generate $\pi' = \pi + \lambda_0 \cdot \tilde{\pi}, \tilde{\pi}$ optimal solution to the problem $DRP(\pi)$. Determine $\lambda_0 = min \left\{ \frac{c_j - \pi^T \cdot a^j}{\tilde{\pi}^T \cdot a^j} / \forall j \in J^c : \tilde{\pi}^T \cdot a^j > 0 \right\}.$ Repeat step 2 until one of the cases 1 or 2 applies.





Illustration



(1) x and π are optimal. Termination
(2) Since b^T · (π + λ₀ · π̃) → ∞,
(P) is not solvable. Termination

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The Primal-Dual Simplex Algorithm

- 1. Transform the problem such that $b \ge 0$ and generate equations.
- 2. Initialization with a feasible basic solution to the dual problem.

3. Determine the set
$$J = \left\{ j = 1, ..., n / \pi^T \cdot a^j = c_j \right\}$$
.

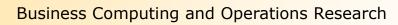
- 4. Solve the reduced primal problem (RP) to optimality via the Primal Simplex Algorithm: $(RP) \xi_0 = Min (1^m)^T \cdot x^a \quad s.t. E_m \cdot x^a + A^J \cdot x^J = b \wedge x^a, x^J \ge 0$
- 5. If $\xi_0 = 0$, then the optimal solution to the primal problem (P) is found. Terminate and calculate the objective function value Z with the basic variables of J: $Z = (c_j)_{j \in J}^T \cdot x^J$ Otherwise (i.e., $\xi_0 > 0$):
- 6. Calculate the dual variables $\tilde{\pi}$ with cost coefficients of RP belonging to x^a : $\tilde{\pi} = 1^m (\overline{c}_j)_{j=1,...,m}$
- 7. If $\xi_0 > 0 \land \forall j : \tilde{\pi}^T \cdot a^j \le 0$, then terminate since the primal problem (P) is unbounded and no optimal solution exists.

Otherwise (i.e., $\xi_0 > 0 \land \exists j : \tilde{\pi}^T \cdot a^j > 0$):

8. Determine
$$\lambda_0 = min\left\{\frac{c_j - \pi^T \cdot a^j}{\tilde{\pi}^T \cdot a^j} \middle| \forall j \notin J : \tilde{\pi}^T \cdot a^j > 0\right\}$$
.

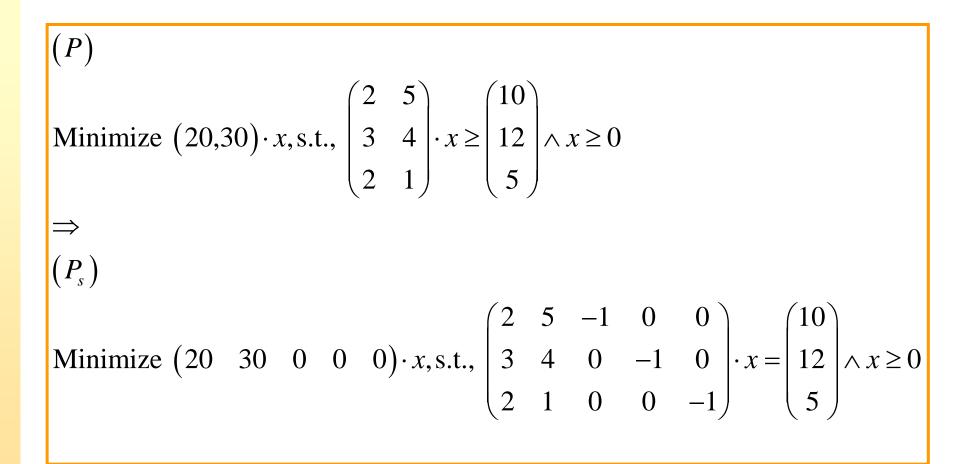
- 9. Update the dual variables: $\pi := \pi + \lambda_0 \cdot \tilde{\pi}$.
- 10. Go to step 3.

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Example







Example

(D)
Maximize
$$(10,12,5,) \cdot \pi, \text{s.t.}, \begin{pmatrix} 2 & 3 & 2 \\ 5 & 4 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \cdot \pi \le \begin{pmatrix} 20 \\ 30 \\ 0 \\ 0 \\ 0 \end{pmatrix} \land \pi \text{ free}$$

Since $c \ge 0$, we can apply the trivial dual solution $\pi = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$.
Thus, we get $J^c = \{1,2\} \land J = \{3,4,5\}$





Example – Generate (RP(π))

 $(RP(\pi))$ Minimize $\begin{pmatrix} 0 & 0 & 0 & 1 & 1 & 1 \end{pmatrix} \cdot x$, s.t. $x \ge 0 \land \begin{pmatrix} -1 & 0 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 & 0 & 1 \end{pmatrix} \cdot x = \begin{pmatrix} 10 \\ 12 \\ 5 \end{pmatrix}$ In order, however, to identify the *j* - values, we integrate the columns of set J^{c} in the tableau as well. Thus, we obtain





Example – Generate λ_0

$$\begin{aligned} \frac{-27}{10} & 0 & 0 & -7 & -10 & 1 & 1 & 1 \\ \hline 10 & 1 & 0 & 0 & 2 & 5 & -1 & 0 & 0 \\ 12 & 0 & 1 & 0 & 3 & 4 & 0 & -1 & 0 \\ 5 & 0 & 0 & 1 & 2 & 1 & 0 & 0 & -1 \\ \Rightarrow & (0 & 0 & 0) = (1 & 1 & 1) - \tilde{\pi} \Leftrightarrow \tilde{\pi} = (1 & 1 & 1) \\ \lambda_0 &= \min\left\{\frac{20 - \pi^T \cdot a^1}{(1 & 1 & 1) \cdot a^1}, \frac{30 - \pi^T \cdot a^2}{(1 & 1 & 1) \cdot a^2}\right\} = \min\left\{\frac{20 - 0}{2 + 3 + 2}, \frac{30 - 0}{5 + 4 + 1}\right\} \\ &= \min\left\{\frac{20}{7}, \frac{30}{10}\right\} = \frac{20}{7} \end{aligned}$$





Example – Generate λ_0

Consequently, we obtain for the next round

$$\pi^{T} = \begin{pmatrix} 0 & 0 & 0 \end{pmatrix} + \frac{20}{7} \cdot \begin{pmatrix} 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{20}{7} & \frac{20}{7} & \frac{20}{7} \end{pmatrix}$$

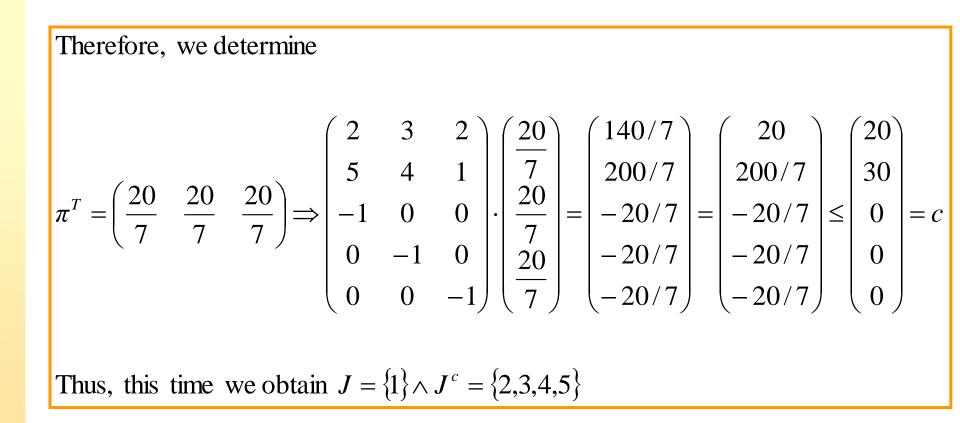
Thus, since $\xi_{0} = 27 > 0$, we get a new $(RP(\pi))$
At first, we have to identify *J*.



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Example – Generate J





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Example – Solving (RP(π))

-27-10-7-27-7|-10() -1-14 0 1 0 -1 -15/2 $0 0 \frac{1}{2}$ $\frac{1}{2}$ (2)0 0 -1 0 1 -10-27-7-1 $-\frac{3}{2}$ 3/2 9/2 $\frac{5}{2}$ 0 -1 $\frac{1}{2}$ $\frac{7}{2}$ -19 $0 -\frac{13}{2} 1 1$ -1 $-\frac{3}{2}$ % $-\frac{1}{2}$





Example – Solving (RP(π))

$$\Rightarrow \left(0, 0, \frac{7}{2}\right) = (1, 1, 1) - \tilde{\pi}^{T} \Leftrightarrow \tilde{\pi}^{T} = \left(1, 1, -\frac{5}{2}\right)$$
$$\Rightarrow \lambda_{0} = \min\left\{\frac{30 - \frac{200}{7}}{5 + 4 - \frac{5}{2}}, \frac{0 - \left(-\frac{20}{7}\right)}{\frac{5}{2}}\right\} = \min\left\{\frac{10}{\frac{7}{13}}, \frac{20}{\frac{7}{5}}\right\}$$
$$= \min\left\{\frac{20}{91}, \frac{40}{35}\right\} = \frac{20}{91}$$





Example – Updating π and J

Consequently, we obtain for the next round

$$\pi^{T} = \left(\frac{20}{7} \quad \frac{20}{7} \quad \frac{20}{7}\right) + \frac{20}{91} \cdot \left(1 \quad 1 \quad -\frac{5}{2}\right) = \left(\frac{40}{13} \quad \frac{40}{13} \quad \frac{30}{13}\right)$$
Thus, since $\xi_{0} = \frac{19}{2} > 0$, we get a new $\left(RP(\pi)\right)$

At first, we again have to identify J.

$$\pi^{T} = \begin{pmatrix} 40 & 40 & 30 \\ 13 & 13 & 13 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 3 & 2 \\ 5 & 4 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 40 \\ 13 \\ 40 \\ 13 \\ 30 \\ 13 \end{pmatrix} = \begin{pmatrix} 260/13 \\ 390/13 \\ -40/13 \\ -40/13 \\ -30/13 \end{pmatrix} = \begin{pmatrix} 20 \\ 30 \\ -40/13 \\ -40/13 \\ -30/13 \end{pmatrix} \leq \begin{pmatrix} 20 \\ 30 \\ 0 \\ 0 \\ 0 \end{pmatrix} = c$$

Thus, this time we obtain $J = \{1, 2\} \land J^c = \{3, 4, 5\}$





Example – Solving (RP(π))

 $\Rightarrow \left(\frac{13}{8}, 0, \frac{15}{8}\right) = \left(1, 1, 1\right) - \widetilde{\pi}^{T} \Leftrightarrow \widetilde{\pi}^{T} = \left(-\frac{5}{8}, 1, -\frac{7}{8}\right)$





Example – Solving (RP(π))

$$\Rightarrow \left(\frac{13}{8}, 0, \frac{15}{8}\right) = (1,1,1) - \tilde{\pi}^{T} \Leftrightarrow \tilde{\pi}^{T} = \left(-\frac{5}{8}, 1, -\frac{7}{8}\right)$$

$$\Rightarrow \lambda_{0} = \min\left\{\frac{\frac{40}{13}, \frac{30}{13}}{\frac{5}{8}}, \frac{\frac{240}{78}}{\frac{7}{8}}\right\} = \frac{240}{91}$$

Thus, we can update π by : $\pi^{T} = \left(\frac{40}{13}, \frac{40}{13}, \frac{30}{13}\right) + \frac{240}{91} \cdot \left(-\frac{5}{8}, 1, -\frac{7}{8}\right)$

$$= \left(\frac{40}{13} - \frac{1200}{728}, \frac{40}{13} + \frac{240}{91}, \frac{30}{13} - \frac{1680}{728}\right)$$

$$= \left(\frac{(2240 - 1200)}{728}, \frac{(280 + 240)}{91}, \frac{(1680 - 1680)}{728}\right)$$

$$= \left(\frac{1040}{728}, \frac{520}{91}, 0\right) = \left(\frac{10}{7}, \frac{40}{7}, 0\right)$$





Example – Updating J

Again, we have to identify
$$J$$
.

$$\pi^{T} = \begin{pmatrix} 10 & 40 & 0 \\ 7 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 3 & 2 \\ 5 & 4 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \cdot \begin{pmatrix} 10/7 \\ 40/7 \\ 0 \\ -10/7 \\ 0 \\ -40/7 \\ 0 \end{pmatrix} = \begin{pmatrix} 20 \\ 30 \\ -10/7 \\ -40/7 \\ 0 \\ -40 \\ -4$$





Example – Solving (RP(π))





Additional literature to Section 5

The primal-dual algorithm for general LP's was first described in

 Dantzig, G.B.: Ford, L.R.; Fulkerson, D.R. (1956): A Primal-Dual Algorithm for Linear Programs," in Kuhn, H.W.; Tucker, A.W. (eds.): *Linear Inequalities and Related Systems.* Princeton University Press, Princeton, N.J., pp. 171-181.

It is introduced there as a generalization of the paper

 Kuhn, H.W. (1955): The Hungarian Method for the Assignment Problem. Naval Research Logistics Quarterly, 2, nos. 1 and 2, pp. 83-97.



